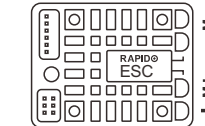


**RAPIDO**  
**ESC**  
ELECTRONIC SPEED CONTROLLER



**PROGRAMABLE ITEM**

1. Running mode: F/B/R mode, F/B mode, F/R crawler mode, the factory default value is F/B/R mode.

The F/B/R mode, that is Forward/Reverse with Brake which provides a reverse function and is suitable for practice. The reverse function is engaged by a Double click method. On the first application of backwards throttle, brakes are applied. On returning to the neutral point, and then applying the backwards throttle for a second time, the reverse function will be engaged. However, if at this time the motor is still moving forward (i.e in a double braking

**DECLARATION**

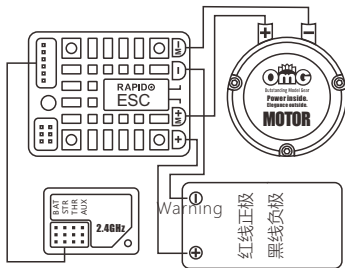
Thank you for purchasing the RCOMG brand RAPIDO series brushed electronic Speed Controller (ESC) for RC Models! Incorrect use may cause personal injury and equipment damage, so please read this manual carefully before using and operate as per the manual guide strictly. We do not assume any liability arising from the use of this product, including but not limited to liability for incidental or consequential damages; at the same time, we do not assume any liability arising from unauthorized modifications to the product. We reserve the right to change product design, appearance, performance and usage requirements without notice.

**FEATURES**

- ◆ Waterproof and dust proof , suitable for various climatic environments;
- ◆ Three running modes ( F/B mode, F/B/R mode, and F/R crawler mode), suitable for various RC cars;
- ◆ 5V/3A BEC output capability;
- ◆ Automatic throttle stroke tuning, easy in operation, friendly for beginners;
- ◆ Unique design for air guide and cooling, better heat dissipation and stronger current resistance;
- ◆ Jumper setting for ESC parameter;
- ◆ Multi Protection Functions, including
- ◆ Motor overheat protection , low voltage cutoff and throttle signal loss protection.

**ESC CONNECTED**

1 This ESC does not have reverse power supply protection. If the power supply is reversed, an



instant irreversible damage to the ESC and the battery may happen.

So Please pay more attention to the polarity of the battery when using it. It is highly recommended to use the battery with antireverse function plug.

2 If the rotation direction of the motor is wrong, please exchange the two wires of the motor.

**RAPIDO-DR-60A**

Forward: continuous current/peak current 60A/360A

Reverse: continuous current/peak current 30A/180A

Voltage range: 2-3S Lipo

Applicable models: 1/10 electric TC, electric buggy, short-course truck, monster, Truck, crawlers

BEC output: 3A / 6V (switch regulator mode)

Fan operating voltage: no fan

支持电机T数	2节锂电	540	≥12T或RPM 低于30000@7.2V
	2节锂电	550	≥18T或RPM 低于20000@7.2V

内阻(单桥臂): 正转: 0.001Ω, 反转: 0.002Ω

Size: 36.5x32x18mm Weight: 39g

具有2对电机输出线, 可驱动2个电机。当同时驱动两个电机时, 所支持的电机T数需要增加。这种情况常见于低速双电机攀爬车。

**THROTTLE RANGE SETTING**

Turn on the transmitter, set the "D/R", "EPA", "ATL" value of the throttle channel to 100% (if the transmitter has no display, turn the corresponding knob to the max), and set the throttle trim to "0" (if the transmitter has no display, turn the corresponding knob to the neutral point).

Please set the throttle channel direction to "REV" for FUTABA and similar transmitters, and set "NOR" for other branded transmitters.

We strongly recommend to turn on the fail-safe protection function of the transmitter, setting the no-signal protection ("F/S") function of the throttle channel to the output turn-off mode or turning the protection value to the neutral point, so that the motor can stop running when the receiver cannot receive signal from transmitter.

**Fault phenomenon Possible reasons**

1 Powered on, no flash, no self-test, and no beep sound.

2 ESC has no working power supply; the ESC switch is damaged.

3 Check whether the power input path from the battery to the ESC has bad welding, and re-weld it; replace the ESC switch.

4 Powered on, LED red flash, and the motor does not run.

The ESC throttle wire is inserted backwards or the channel is incorrect; the ESC cannot successfully complete the throttle self-checking and tuning process.

5 Insert the ESC throttle wire into the receiver throttle channel (Throttle, channel 2) in the correct direction; set the throttle trim to "0" or turn the corresponding knob to the neutral point

**Fault phenomenon Possible reasons**

1 Throttle engage Forward , but the car reverses.

2 The direction of the throttle channel of the transmitter is incorrectly set or the wiring of the motor is incorrect.

3 Swap the two wires of the motor; reverse the throttle channel of the transmitter, Changing from the original "NOR" to "REV" or from the original "REV" to "NOR".

4 Throttle cannot reach to full speed, the Throttle stick is at the Max, and the LED not solid red

5 The transmitter settings are wrong.

6 Set the "D/R", "EPA", "ATL" value of the throttle channel to 100% or turn the corresponding knob to the max), and set the throttle trim to "0" or turn the corresponding knob to the neutral point.

Switch on the ESC , with the transmitter stick at neutral point, and wait until the ESC self-check and auto-throttle calibration process finished (within 3 seconds). It will be in normal running after hearing the self-check success beep.

**Number of battery cells and self-test beep sound indication**

1 short beep sound	NiMH NiCd battery
2 short beep sound	2S lipo
3 short beep sound	3S lipo
4 short beep sound	4S lipo
1 long beep sound	Success of throttle self-checking and tuning

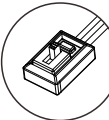
**LED Status in Normal Running**

LED red no flash	the throttle stick is in the neutral range
LED red flash	forward, brake, reverse under non-full throttle
LED red solid bright	forward, brake, reverse under full throttle

**Direction of the position status of the transmitter throttle stick**

打开电调开关

摇杆置于中点



**PARAMETER SETTING METHOD**

ESC adopts jumper cap setting method, which can be set to running mode and battery type Setting method: It is recommended to use tweezers and refer to the diagram below, unplugging the jumper cap to set the parameter; if you want to set the battery type to "Lipo" mode, just insert the jumper cap into the two PINs on the left side of the battery.

**Fault phenomenon Possible reasons**

1 The car can't move forward or reverse, and the LED status is normal.

2 The connection between the ESC and the motor is broken; the motor is damaged.

3 Check the connection between the motor and the ESC to make sure the connection is reliable; replace the motor with a new one.

4 When the motor starts , it accelerates rapidly, and the motor gets stuck or stops sometimes.

5 Battery discharging is not enough ; the motor speed is too high and the gear ratio is too aggressive; there is a problem with the car transmission system.

6 Replace the battery with strong discharge capacity; replace the low-speed motor, or increase the reduction ratio; Check the car transmission system to make sure it smooth.